# A Report on Generalized Trigonometric Functions, Product Formulas, and Group Convolutions

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#### 1 An Analogue to the Basel Problem

This section, based on work from 12.12.2021, explores a function analogous to the sinc function used in the resolution of the Basel problem.

Let us define the function f(x) as the infinite product:

$$f(x) = \prod_{n=1}^{\infty} \left( 1 + \frac{x^3}{n^3} \right)$$

Using the roots of unity, where  $\omega = \exp(\frac{2\pi i}{3})$ , this can be factored as:

$$f(x) = \prod_{n=1}^{\infty} \left(1 + \frac{x}{n}\right) \left(1 + \frac{x}{n}\omega\right) \left(1 + \frac{x}{n}\omega^2\right)$$

Expanding this product into a power series gives a representation in terms of generalized elementary symmetric polynomials:

$$f(x) = \sum_{k=0}^{\infty} \zeta_k(3) x^{3k}$$

where we define:

$$\zeta_k(3) = \sum_{1 \le n_1 < n_2 < \dots < n_k} \left(\frac{1}{n_1 n_2 \cdots n_k}\right)^3$$

with  $\zeta_0(3) = 1$  and  $\zeta_1(3) = \zeta(3)$ .

Inspired by the Euler reflection formula for the sinc function, we conjecture a similar identity for f(x).

**Conjecture 1.1.** The function f(x) satisfies the reflection-type formula:

$$f(x) = \frac{1}{\Gamma(1+x)\Gamma(1+\omega x)\Gamma(1+\omega^2 x)}$$

A series expansion of the right-hand side of the conjecture using SageMath yields coefficients that relate  $\zeta_k(3)$  to powers of  $\pi$  and values of the Riemann zeta function.

$$\begin{split} \zeta_1(3)x^3 &= \zeta(3)x^3 \\ \zeta_2(3)x^6 &= \left(-\frac{\pi^6}{1890} + \frac{1}{2}\zeta(3)^2\right)x^6 = -\frac{1}{1890}\left(\pi^6 - 945\,\zeta(3)^2\right)x^6 \\ \zeta_3(3)x^9 &= \left(-\frac{\pi^6\zeta(3)}{1890} + \frac{1}{6}\zeta(3)^3 + \frac{1}{3}\zeta(9)\right)x^9 = -\frac{1}{1890}\left(\pi^6\zeta(3) - 315\,\zeta(3)^3 - 630\,\zeta(9)\right)x^9 \\ \zeta_4(3)x^{12} &= -\frac{1}{5108103000}\left(667\,\pi^{12} + 1351350\,\pi^6\zeta(3)^2 - 212837625\,\zeta(3)^4 - 1702701000\,\zeta(9)\zeta(3)\right)x^{12} \\ \zeta_5(3)x^{15} &= -\frac{1}{5108103000}\left(667\pi^{12}\zeta(3) + 450450\pi^6\zeta(3)^3 + 900900\pi^6\zeta(9) \\ &\quad -42567525\zeta(3)^5 - 851350500\zeta(9)\zeta(3)^2 - 1021620600\zeta(15)\right)x^{15} \end{split}$$

From these identities, one could potentially solve for  $\zeta(3)$ . For instance, from the coefficient of  $x^6$ :

$$\zeta(3) = \sqrt{\frac{1890\,\zeta_2(3) + \pi^6}{945}}$$

This raises several questions:

1. Is the conjectured "reflection" equality true?

- 2. Is there a "closed formula" for the  $\zeta_k(3)$  coefficients, or are they related to known numbers in a systematic way?
- 3. Can this procedure be generalized to products of the form  $\prod (1 \frac{x^l}{n^l})$ ?
- 4. Is there established literature on the function f(x)?

#### **Proof of the Reflection Formula**

As noted by Terry Tao in a related context, we can use the Weierstrass factorization of the Gamma function:

$$\Gamma(z) = \frac{e^{-\gamma_E z}}{z} \prod_{k=1}^{\infty} \left(1 + \frac{z}{k}\right)^{-1} e^{z/k}$$

Applying this for  $z = x, \omega x, \omega^2 x$  and multiplying the three results, the exponential terms cancel because  $1 + \omega + \omega^2 = 0$ . This gives:

$$\begin{split} \Gamma(x)\Gamma(\omega x)\Gamma(\omega^2 x) &= \frac{e^{-\gamma_E x(1+\omega+\omega^2)}}{x\cdot\omega x\cdot\omega^2 x}\prod_{k=1}^{\infty}\left(\left(1+\frac{x}{k}\right)\left(1+\frac{\omega x}{k}\right)\left(1+\frac{\omega^2 x}{k}\right)\right)^{-1}e^{x(1+\omega+\omega^2)/k}\\ &= \frac{1}{x^3}\prod_{k=1}^{\infty}\left(1+\frac{x^3}{k^3}\right)^{-1} \end{split}$$

and therefore

$$\prod_{k=1}^{\infty} \left( 1 + \frac{x^3}{k^3} \right) = \frac{1}{x^3 \Gamma(x) \Gamma(\omega x) \Gamma(\omega^2 x)}$$

Using the functional equation  $\Gamma(1+z) = z\Gamma(z)$  for  $z = x, \omega x, \omega^2 x$ , we have:

$$\Gamma(1+x)\Gamma(1+\omega x)\Gamma(1+\omega^2 x) = (x\Gamma(x))(\omega x\Gamma(\omega x))(\omega^2 x\Gamma(\omega^2 x)) = x^3\Gamma(x)\Gamma(\omega x)\Gamma(\omega^2 x)$$

Combining these two results confirms the conjecture:

$$f(x) = \prod_{k=1}^{\infty} \left( 1 + \frac{x^3}{k^3} \right) = \frac{1}{\Gamma(1+x)\Gamma(1+\omega x)\Gamma(1+\omega^2 x)}$$

This procedure generalizes directly to  $f_l(x) = \prod_{n=1}^{\infty} (1 + (x/n)^l)$  for  $l \ge 2$ .

# An Identity for $\sum 1/(n^3+1)$

Let's analyze the sum  $\sum_{n=1}^{\infty} \frac{1}{n^3+1}$ . Consider the function  $c_0(x) = xf(\frac{x}{\pi})$ . Using the product form of f(x):

$$\frac{c_0(\pi x)}{\pi x} = f(x) = \prod_{n=1}^{\infty} \left(1 + \frac{x^3}{n^3}\right)$$

Taking the logarithmic derivative with respect to x:

$$\frac{d}{dx}\log\left(\frac{c_0(\pi x)}{\pi x}\right) = \frac{\pi c_0'(\pi x)}{c_0(\pi x)} - \frac{1}{x} = \sum_{n=1}^{\infty} \frac{3x^2}{n^3 + x^3}$$

Dividing by 3 and setting x = 1, we find:

$$\frac{\pi c_0'(\pi)}{3c_0(\pi)} - \frac{1}{3} = \sum_{n=1}^{\infty} \frac{1}{n^3 + 1}$$

To evaluate the left-hand side, we use the Gamma function representation of  $c_0(x)$ :

$$c_0(x) = \frac{x}{\Gamma(1 + \frac{x}{\pi})\Gamma(1 + \omega\frac{x}{\pi})\Gamma(1 + \omega^2\frac{x}{\pi})}$$

Its logarithmic derivative is:

$$\frac{c_0'(x)}{c_0(x)} = \frac{1}{x} - \frac{1}{\pi}\psi\left(1 + \frac{x}{\pi}\right) - \frac{\omega}{\pi}\psi\left(1 + \omega\frac{x}{\pi}\right) - \frac{\omega^2}{\pi}\psi\left(1 + \omega^2\frac{x}{\pi}\right)$$

where  $\psi(z) = \Gamma'(z)/\Gamma(z)$  is the digamma function. Evaluating at  $x = \pi$ :

$$\frac{c'_0(\pi)}{c_0(\pi)} = \frac{1}{\pi} - \frac{1}{\pi}\psi(2) - \frac{\omega}{\pi}\psi(1+\omega) - \frac{\omega^2}{\pi}\psi(1+\omega^2)$$

Substituting this into our expression for the sum gives:

$$\sum_{n=1}^{\infty} \frac{1}{n^3 + 1} = \frac{\pi}{3} \left( \frac{1}{\pi} - \frac{\psi(2)}{\pi} - \frac{\omega\psi(1 + \omega)}{\pi} - \frac{\omega^2\psi(1 + \omega^2)}{\pi} \right) - \frac{1}{3}$$
$$= \frac{1}{3} \left( 1 - \psi(2) - \omega\psi(1 + \omega) - \omega^2\psi(1 + \omega^2) \right)$$

Using  $\psi(2) = 1 - \gamma_E$  and  $1 = -\omega - \omega^2$ , we get:

$$\sum_{n=1}^{\infty} \frac{1}{n^3 + 1} = \frac{1}{3} \left( \gamma_E - \omega \psi (1 + \omega) - \omega^2 \psi (1 + \omega^2) \right)$$

This expression can be further manipulated, providing a closed-form representation for the sum in terms of special functions.

## 2 Functions for the Cyclic Group $C_3$

This section (from 20.12.2021) develops function analogues of sinh,  $\cosh, \sin, \cos$  for the cyclic group  $C_3$ .

Define the functions  $t_k(x)$  for k = 0, 1, 2:

$$t_k(x) = \sum_{n=0}^{\infty} \frac{x^{3n+k}}{(3n+k)!}$$

These functions are the components of the exponential function projected onto the eigenspaces of the  $C_3$  action. They are related via the character table of  $C_3$ , where  $\omega = \exp(2\pi i/3)$ :

$$\begin{pmatrix} \exp(x) \\ \exp(\omega x) \\ \exp(\omega^2 x) \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & \omega & \omega^2 \\ 1 & \omega^2 & \omega \end{pmatrix} \cdot \begin{pmatrix} t_0(x) \\ t_1(x) \\ t_2(x) \end{pmatrix}$$

From this relationship, one can derive the following addition theorem, where the matrix is circulant:  $(t_{1}(t_{1})) = (t_{2}(t_{1})) = (t_{2}(t_{1}))$ 

$$\begin{pmatrix} t_0(x+y) \\ t_1(x+y) \\ t_2(x+y) \end{pmatrix} = \begin{pmatrix} t_0(x) & t_2(x) & t_1(x) \\ t_1(x) & t_0(x) & t_2(x) \\ t_2(x) & t_1(x) & t_0(x) \end{pmatrix} \cdot \begin{pmatrix} t_0(y) \\ t_1(y) \\ t_2(y) \end{pmatrix}$$

The determinant of this circulant matrix gives a fundamental identity, analogous to  $\cosh^2(x) - \sinh^2(x) = 1$ :

$$t_0(x)^3 + t_1(x)^3 + t_2(x)^3 - 3t_0(x)t_1(x)t_2(x) = 1, \quad \forall x \in \mathbb{C}$$

We can also define trigonometric analogues. Let  $\gamma = \exp(\frac{2\pi i}{9})$ . Set:

- $s_0(x) := \frac{1}{\gamma} t_0(\gamma x)$
- $s_2(x) := s'_0(x) = t_2(\gamma x)$
- $s_1(x) := s'_2(x) = \gamma t_1(\gamma x)$

From the derivative relations  $t'_0 = t_2$ ,  $t'_2 = t_1$ ,  $t'_1 = t_0$ , it follows that  $s'_1(x) = \gamma^2 s_0(x)$ . These functions satisfy their own addition theorem and a determinant identity analogous to  $\sin^2(x) + \cos^2(x) = 1$ :

$$\gamma^3 s_0(x)^3 + s_2(x)^3 + \frac{s_1(x)^3}{\gamma^3} - 3s_0(x)s_1(x)s_2(x) = 1$$

#### **3** Generalization to Finite Groups

This section (based on notes from 23.10.2021) generalizes the previous construction from  $C_3$  to any finite group G.

For a finite group G, we seek functions  $t_g(x)$  for  $g \in G$  that satisfy the convolution-style addition formula:

$$t_g(x+y) = \sum_{h \in G} t_{gh^{-1}}(x)t_h(y)$$

This can be written as  $t_{x+y}(g) = (t_x * t_y)(g)$ , where  $t_x$  is the function  $g \mapsto t_g(x)$  and \* is the group convolution.

The Fourier transform of a convolution is the product of the Fourier transforms. Let  $\rho$  be an irreducible representation of G. The Fourier transform of  $t_x$  is:

$$\widehat{t}_x(\rho) = \sum_{g \in G} t_g(x)\rho(g)$$

The addition formula is satisfied if  $\widehat{t_{x+y}}(\rho) = \widehat{t_x}(\rho)\widehat{t_y}(\rho)$ . This is a homomorphism property, satisfied by an exponential function.

Let  $S = \{s_1, \ldots, s_r\}$  be a generating set for G with  $1 \notin S$ . Let  $x = (x_{s_i})_{s_i \in S}$  be a vector of variables. We can define the functions  $t_g$  via their Fourier transform:

$$\widehat{t_x}(\rho) := \exp\left(\frac{1}{d_{\rho}}\sum_{s\in S}\chi_{\rho}(s)x_s\right)\mathbf{1}_{d_{\rho}}$$

where  $d_{\rho}$  is the dimension of  $\rho$ ,  $\chi_{\rho}$  is its character, and  $\mathbf{1}_{d_{\rho}}$  is the identity matrix. This definition immediately ensures that  $\widehat{t_{x+y}}(\rho) = \widehat{t_x}(\rho)\widehat{t_y}(\rho)$ .

Applying the inverse Fourier transform, we obtain an explicit formula for the functions:

$$t_g(x) = \frac{1}{|G|} \sum_{\rho \text{ irred.}} d_\rho \operatorname{Tr}\left(\rho(g^{-1})\widehat{t_x}(\rho)\right) = \frac{1}{|G|} \sum_{\rho \text{ irred.}} d_\rho \chi_\rho(g^{-1}) \exp\left(\frac{1}{d_\rho} \sum_{s \in S} \chi_\rho(s) x_s\right)$$

From this formula, we see that  $t_g(x)$  depends only on the conjugacy class of g.

Furthermore, the determinant of the group matrix  $T_G = (t_{gh^{-1}}(x))_{g,h\in G}$  can be evaluated

using the Frobenius determinant formula:

$$\det(T_G) = \prod_{\rho \text{ irred.}} \det\left(\sum_{g \in G} t_g(x)\rho(g)\right)^{d_{\rho}} = \prod_{\rho \text{ irred.}} \det(\widehat{t_x}(\rho))^{d_{\rho}}$$
$$= \prod_{\rho \text{ irred.}} \det\left(\mathbf{1}_{d_{\rho}} \exp\left(\frac{1}{d_{\rho}}\sum_{s \in S} \chi_{\rho}(s)x_s\right)\right)^{d_{\rho}}$$
$$= \prod_{\rho \text{ irred.}} \left(\exp\left(\frac{1}{d_{\rho}}\sum_{s \in S} \chi_{\rho}(s)x_s\right)\right)^{d_{\rho}^2} = \exp\left(\sum_{\rho \text{ irred.}} d_{\rho}\sum_{s \in S} \chi_{\rho}(s)x_s\right)$$
$$= \exp\left(\sum_{s \in S} x_s\left(\sum_{\rho} d_{\rho}\chi_{\rho}(s)\right)\right)$$

The inner sum  $\sum_{\rho} d_{\rho} \chi_{\rho}(s)$  is the value of the regular character on s. For any  $s \neq 1$ , this sum is zero. Since we chose  $1 \notin S$ , we have:

$$\det(T_G) = \exp(0) = 1$$

#### Example: The Symmetric Group $S_3$

For  $G = S_3$ , with generating set  $S = \{(1, 2), (2, 3)\}$  and variables  $x_0, x_1$ , the functions are:

• For  $g \in \{e, (123), (132)\}$  (conjugacy class of the identity and 3-cycles):

$$t_e(x_0, x_1) = \frac{1}{6}e^{x_0 + x_1} + \frac{1}{6}e^{-x_0 - x_1} + \frac{2}{3}$$
$$t_{(123)}(x_0, x_1) = t_{(132)}(x_0, x_1) = \frac{1}{6}e^{x_0 + x_1} + \frac{1}{6}e^{-x_0 - x_1} - \frac{1}{3}$$

• For  $g \in \{(12), (13), (23)\}$  (conjugacy class of transpositions):

$$t_g(x_0, x_1) = \frac{1}{6}e^{x_0 + x_1} - \frac{1}{6}e^{-x_0 - x_1}$$

#### SageMath Implementation

Listing 1: SageMath code to compute  $t_q(x)$  for S3

```
G = SymmetricGroup(3)
# S = [G[3], G[5]] # Corresponds to S = {(1,2),(2,3)}
S = [list(G)[-3],list(G)[-1]] # A more robust way to select generators
X = var([("x"+str(i)) for i in range(len(S))])
# Define irreducible representations for S3
trivial = G.irreducible_characters()[0].to_representation()
sign = G.irreducible_characters()[1].to_representation()
standard = G.irreducible_characters()[2].to_representation()
irredPerms = [trivial, sign, standard]
def log_inverse_Fourier(rep, X_vars):
    m = sum([rep(S[i]).trace() * X_vars[i] for i in range(len(S))])
    return m
```

```
s = 0
    for rho in irredPerms:
        em = exp(log_inverse_Fourier(rho, X_vars))
        s += rho(Permutation([1,2,3])).degree() * (rho(perm.inverse())
            * em).trace()
    return 1/G.order() * s
# Verify the addition theorem
var("a0,a1,b0,b1")
X_val = [a0, a1]
Y_val = [b0, b1]
Z_val = [X_val[i] + Y_val[i] for i in range(2)]
for g in G:
    lhs = tau(g, Z_val)
    rhs = sum([tau(g*h.inverse(), Y_val) * tau(h, X_val) for h in G])
    print(f"Permutation_{\sqcup}g_{\sqcup}=_{\sqcup}\{g\}")
    # The symbolic verification can be slow/complex
    # print("Addition theorem satisfied:", bool(expand(lhs - rhs) == 0)
    print(f"t_g(a_0,a_1)_{\sqcup}=_{\sqcup}{factor(tau(g,X_val))}/n")
```

## 4 Associated Partial Differential Equations

For a finite abelian group G (written additively for this section), the formulas from Section 3 simplify. The representations are 1-dimensional characters, so  $d_{\rho} = 1$  and  $\chi_{\rho}(g) = \rho(g)$ .

$$t_g(x) = \frac{1}{|G|} \sum_{\rho \text{ irred.}} \rho(-g) \exp\left(\sum_{s \in S} \rho(s) x_s\right)$$

Let us differentiate with respect to a variable  $x_{s_0}$  for  $s_0 \in S$ :

$$\frac{\partial t_g(x)}{\partial x_{s_0}} = \frac{1}{|G|} \sum_{\rho \text{ irred.}} \rho(-g)\rho(s_0) \exp\left(\sum_{s \in S} \rho(s)x_s\right)$$
$$= \frac{1}{|G|} \sum_{\rho \text{ irred.}} \rho(-(g-s_0)) \exp\left(\sum_{s \in S} \rho(s)x_s\right)$$
$$= t_{g-s_0}(x)$$

By induction, for any  $h = \sum_{i=1}^{r} e_i s_i \in G$ , we can define a higher-order partial derivative:

$$\frac{\partial t_g(x)}{\partial h} := \frac{\partial^{e_1 + \dots + e_r} t_g(x)}{\partial x_{s_1}^{e_1} \cdots \partial x_{s_r}^{e_r}} = t_{g-h}(x)$$

This means the group G acts on the set of functions  $\{t_g(x)\}$  via differentiation. Since  $t_{g-h}(x) = t_{(g-h)e^{-1}}(x) = t_{gh^{-1}}(x)$  in multiplicative notation, and we proved that  $\det(t_{gh^{-1}}(x)) = 1$ , we arrive at a remarkable PDE satisfied by the vector of functions  $T(x) = (t_g(x))_{g \in G}$ :

$$\det\left(\left(\frac{\partial t_g(x)}{\partial h}\right)_{g,h\in G}\right) = 1$$

### 5 Monge–Ampère Equation, 04.01.2022

Let G be a finite abelian group (written additively) and let  $X = (x_g)_{g \in G}$  be the corresponding vector of variables. For each  $g \in G$ , define

$$\tau_g(X) := \frac{1}{|G|} \sum_{\rho \text{ irred.}} \chi_\rho(-g) \exp\left(\sum_{s \in G} \chi_\rho(s) x_s\right),$$

where the sum runs over all irreducible characters  $\rho$  of G. Then one checks immediately that

$$\frac{\partial}{\partial x_h} \tau_g(X) = \tau_{g-h}(X).$$

 $\operatorname{Set}$ 

$$u(X) := \tau_0(X).$$

Its Hessian matrix is

$$H_u(X) = \left[\partial_{x_g}\partial_{x_h} u(X)\right]_{g,h\in G} = \left[\tau_{-(g+h)}(X)\right]_{g,h\in G}$$

Hence the "discrete Monge–Ampère equation" becomes

$$\det H_u(X) = \det (\tau_{-(g+h)}(X))_{g,h\in G} = \pm \det (\tau_{g-h}(X))_{g,h\in G},$$

where the sign  $\pm$  arises from the permutation  $g \mapsto -g$  on the rows. The determinant  $\det(\tau_{g-h})$  is exactly the classical group determinant  $\det[a_{gh^{-1}}]_{g,h\in G}$  with  $a_g = \tau_g(X)$ , which by Frobenius's theorem factors as

$$\det(\tau_{g-h}) = \prod_{\rho \text{ irred.}} \det\left(\sum_{g \in G} \tau_g(X) \rho(g)\right)^{\dim \rho}.$$

Thus imposing

$$\det H_u(X) = f(X)$$

amounts to finding the vector  $(\tau_g(X))$  whose group determinant matches the prescribed function f(X) — in other words, to solving a Monge–Ampère–type equation in the discrete variables  $\{x_g\}$ .

#### 6 Speculations on the Navier-Stokes Equations

This final section (from 30.12.2021) explores a potential connection between the functions developed above and the Navier-Stokes equations for incompressible fluid flow.

Let G be a finite abelian group and  $X = (x_g)_{g \in G}$  be a vector of variables, one for each group element. Define the functions:

$$\tau_g(X) := \frac{1}{|G|} \sum_{\rho \text{ irred.}} \rho(-g) \exp\left(\sum_{s \in G} \rho(s) x_s\right)$$

These functions satisfy the simple differentiation rule:

$$\frac{\partial \tau_g(X)}{\partial x_h} = \tau_{g-h}(X)$$

Now consider the advection term in the Navier-Stokes equations, which has the form  $(u \cdot \nabla)u$ . In our discrete setting, this corresponds to a sum:

$$\sum_{h \in G} u_h(X) \frac{\partial u_g(X)}{\partial x_h}$$

If we set  $u_g = \tau_g$ , we find a convolution identity:

$$\sum_{h \in G} \tau_h(X) \frac{\partial \tau_g(X)}{\partial x_h} = \sum_{h \in G} \tau_h(X) \tau_{g-h}(X) = (\tau_X * \tau_X)(g) = \tau_g(2X)$$

This structural similarity suggests that these functions might be useful building blocks for solutions.

Let us attempt to construct a solution to the sourceless Navier-Stokes equations in  $\mathbb{R}^n \times [0,\infty)$ :

$$\frac{\partial u}{\partial t} - \nu \Delta u + (u \cdot \nabla)u + \nabla p = 0 \text{ and } \nabla \cdot u = 0$$

Let  $G = C_n$  be a cyclic group of odd order n. Let the spatial variables be  $X = (x_g)_{g \in G}$ . We propose a velocity field  $u(t, X) = (u_g(t, X))_{g \in G}$  and pressure p(t, X).

Let  $\alpha_g(X) := \tau_g(-X) - \tau_{g-1}(-X)$ . This combination has zero divergence:

$$\nabla \cdot \alpha = \sum_{g \in G} \frac{\partial \alpha_g}{\partial x_g} = \sum_{g \in G} \left( \frac{\partial \tau_g(-X)}{\partial x_g} - \frac{\partial \tau_{g-1}(-X)}{\partial x_g} \right) = \sum_{g \in G} (\tau_{g-g}(-X) - \tau_{g-1-g}(-X)) = \sum_{g \in G} (\tau_0(-X) - \tau_{-1}(-X))$$

Since n is odd,  $h \mapsto 2h$  is a permutation of G, so  $\Delta \alpha_g = \sum_h \alpha_{g-2h} = \sum_k \alpha_k = 0$ . So  $\alpha$  is harmonic.

Let's propose a solution of the form  $u_g(t, X) := t\alpha_g(X) + u_g^0(X)$ , where  $u^0$  is a given divergence-free initial condition at t = 0.

- 1. Initial Condition:  $u(0, X) = u^0(X)$ . This is satisfied by construction.
- 2. Incompressibility:  $\nabla \cdot u = \nabla \cdot (t\alpha + u^0) = t(\nabla \cdot \alpha) + (\nabla \cdot u^0) = 0 + 0 = 0$ . This holds.

Substituting into the momentum equation:

$$\frac{\partial u_g}{\partial t} + \sum_{h \in G} u_h \frac{\partial u_g}{\partial x_h} - \nu \Delta u_g + \frac{\partial p}{\partial x_g} = 0$$
  
$$\alpha_g + \sum_h (t\alpha_h + u_h^0)(t\alpha_{g-h} + \frac{\partial u_g^0}{\partial x_h}) - \nu \Delta (t\alpha_g + u_g^0) + \frac{\partial p}{\partial x_g} = 0$$
  
$$\alpha_g + t^2 (\alpha * \alpha)_g + t(\alpha * \partial u_g^0)_g + t(u^0 \cdot \nabla)\alpha_g + (u^0 \cdot \nabla)u_g^0 - \nu \Delta u_g^0 + \frac{\partial p}{\partial x_g} = 0$$

Using  $\Delta \alpha = 0$  and the initial condition  $(u^0 \cdot \nabla)u_g^0 - \nu \Delta u_g^0 + \nabla_g p^0 = 0$ , this simplifies. The construction raises several difficult questions:

**Question 6.1.** Does the vector field  $\alpha_g(X)$  satisfy the Euler equations (the NS equations with  $\nu = 0$ ) for some pressure function  $p_\alpha$ ? That is, can we find  $p_\alpha$  such that  $\nabla_g p_\alpha = -(\alpha * \alpha)_g$ ?

**Question 6.2.** Can one find a pressure p(t, X) that absorbs all the gradient terms arising from the expansion?

This approach recasts the non-linear advection term as a structured convolution, which may offer a new perspective, but its ultimate utility in solving this notoriously difficult problem remains an open question.